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[5.1 Inverse Kinematics](#)

5.1 Inverse Kinematics von Woolfrey vor 2 Jahren 8 Minuten, 54 Sekunden 8.542 Aufrufe In this lecture, I introduce the concept of Inverse , Kinematics , (IK). That is, for a given end-effector pose of the , robot , we want to find a ...

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